



**Leadshine**

Stock Code: 002979



**CODESYS**



**Modbus**



**OPC UA**



**CANopen**



**EtherNet/IP™**



**EtherCAT®**

# MC500 series

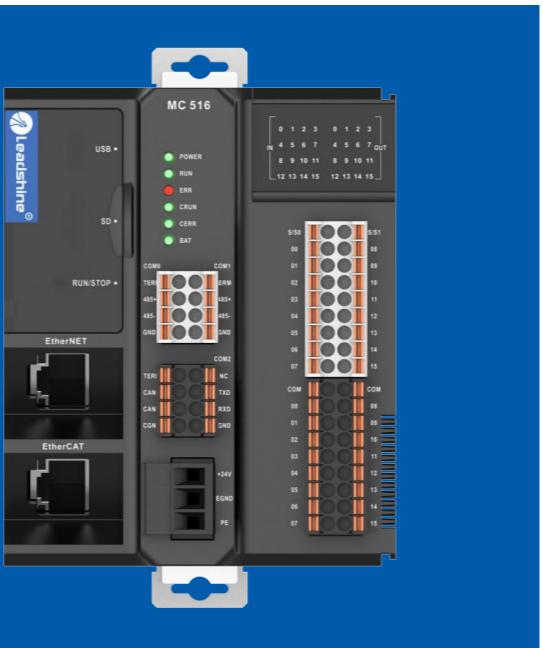
**General Type EtherCAT Bus PLC**

## Stable Efficient Easy to use

In industries such as photovoltaic, semiconductor, electronics, CNC and logistics, alongside the upcoming of China's Intelligence Manufacturing 2025, there is a need to improve equipment efficiency and ease-of-use, as well as cost reduction. We need to find a more user-friendly, expandable and highly integrated control solution to achieve efficient operation throughout the

entire installation process from wiring, programming, debugging and application. Leadshine has launched a new economical bus type controller MC500 series to meet the increasingly high demands of motion control. MC500 series controller has a more complete functionalities for smart devices connection applications.

- Balancing motion control, complete functionality, and intelligent connectivity greatly
- Reduces user device development time, improving efficiency by 30% compared to traditional development models



### Features

#### Motion control

- EtherCAT 32 axes
- 200kHz high-speed pulse 6 axes
- 6 axes linear / 3 axes circular interpolation
- E-CAM/flying shear/chasing shear

#### Intelligent interconnection

- OPC UA
- EtherNET/IP
- 32 CANopen distributed control
- Modbus/Free communication port

#### Rich functionality

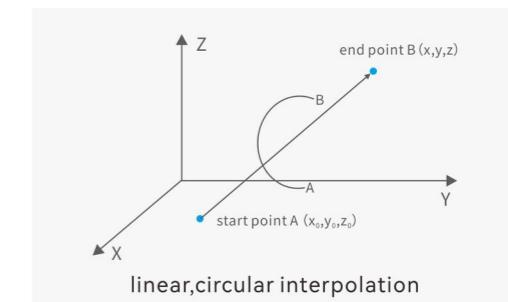
- local bus expand 32 I/O modules
- 32767 I/O
- 6 200kHz high-speed counting
- over temperature, over voltage, short circuit protection

## Motion control 6 high-speed pulse axes + 32 EtherCAT axes

The excellent performance of a dual core SOC+FPGA high-speed processor enables motion control functions such as positioning, interpolation, and E-CAM that comply with PLCopen standards.

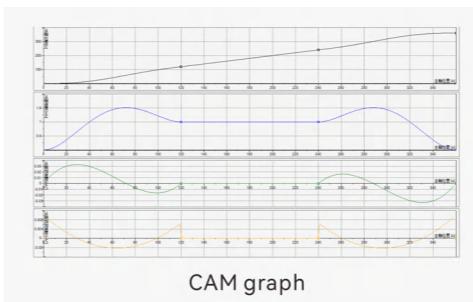
### Interpolation

Multidimensional linear interpolation, circular interpolation, and continuous interpolation can be used to control the trajectory for machining with certain precision and high-speed positioning transmission according to the shortest route.



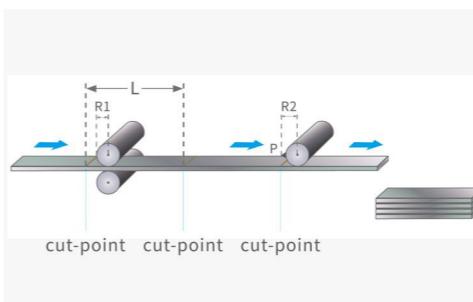
### E-CAM

By digitizing cam movements, the problems of low precision, easy wear and noise in mechanical cams can be solved.



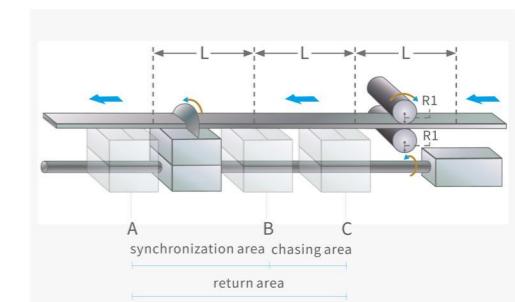
### Flying Shear

By setting values such as cutting length, number of cutting heads, and synchronization zone through process parameters, a rotary cutting cam table can be established within the synchronization zone, with the spindle and slave shafts operating at a certain speed ratio.



### Chasing Shear

By setting values such as cutting length, waiting position, chasing area, synchronization area, and return area through process parameters, a chasing cam table can be established, which is suitable for application scenarios such as cutting and filling.



**PLC**

**digital module**

**analog module**

**temperature module**

**encoder module**

**I/O**

integrated 32 IO(16 inputs 16 outputs)  
 • 6\*200kHz high-speed pulse  
 • output 6\*200kHz high-speed counting  
 •

**Program**

- Type-C port
- upload or download program

**Save**

- Optional SD card
- download program ,save data

**Serial port**

- 2\*RS485,1\*RS232
- Integrated serial port adapted instrument connection

**Ethernet**  

- OPC UA,EtherNet/IP
- Modbus-TCP,Socket

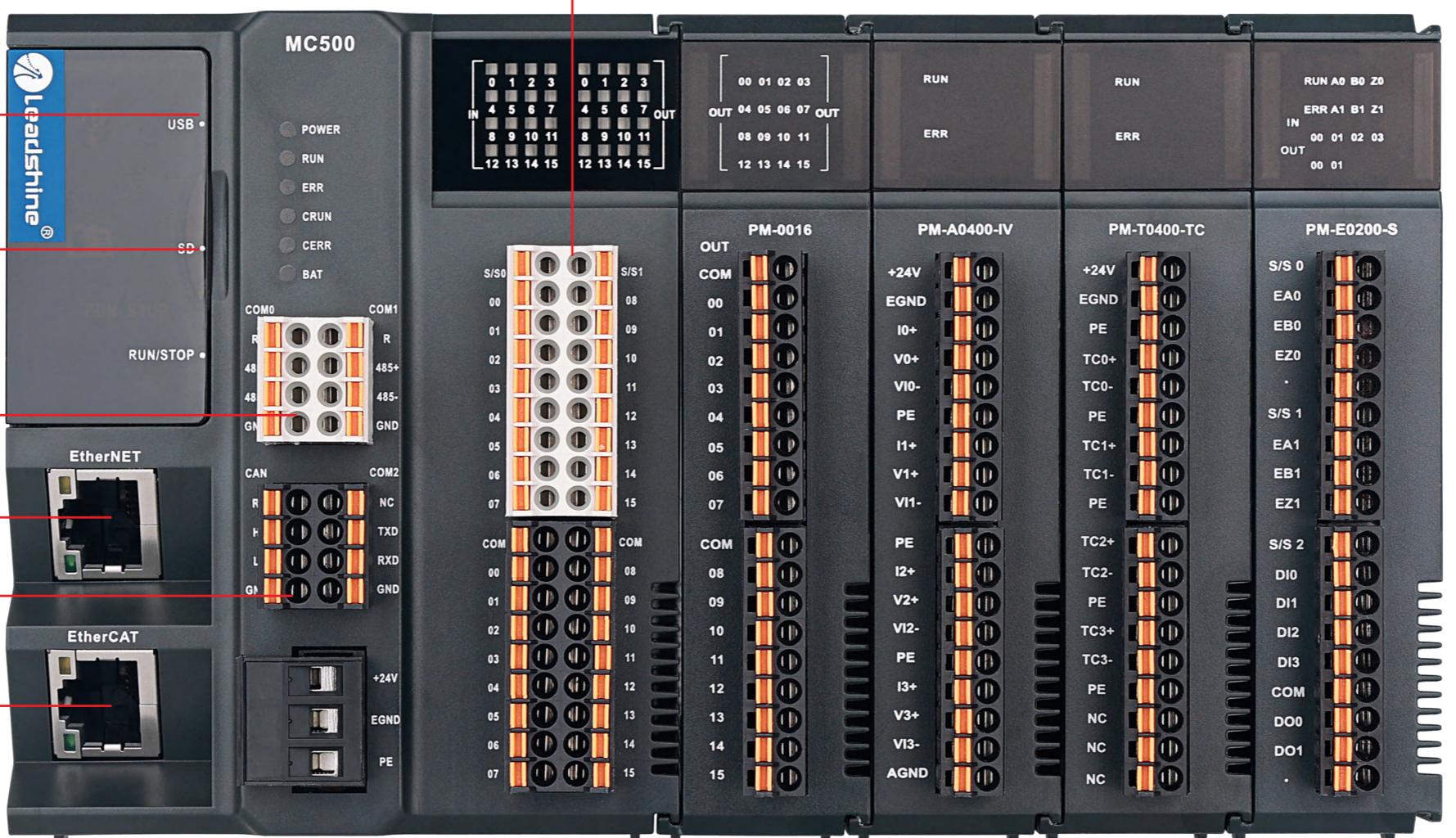
**Motion control** 

- maximum control 32 axes
- Configure up to 128 EtherCAT slaves

**Distributed** 

- The farthest transmission
- distance : 2.5km Configure up to 31 CANopen slaves

**Application**  
photovoltaic, Lithium battery, semiconductor, 3C, Logistics industry, packing, Special machine tool industry ect.

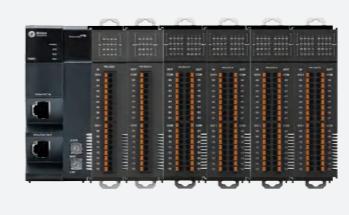
  
The MC500 PLC main unit features a central processing unit (CPU) with integrated motion control and a backplane bus. It includes various communication ports (USB, SD, EtherNET, EtherCAT) and a range of I/O modules. A red box highlights the integrated I/O section, which consists of 16 inputs and 16 outputs, each supporting 6\*200kHz high-speed pulse and output. The I/O assignments are as follows:  
 - Input 00: +24V  
 - Input 01: EGND  
 - Input 02: IO+  
 - Input 03: V0-  
 - Input 04: PE  
 - Input 05: I1+  
 - Input 06: V1+  
 - Input 07: VI1-  
 - Input 08: COM  
 - Input 09: 00  
 - Input 10: 01  
 - Input 11: 02  
 - Input 12: 03  
 - Input 13: 04  
 - Input 14: 05  
 - Input 15: 06  
 - Output 00: S/S 0  
 - Output 01: EA0  
 - Output 02: EB0  
 - Output 03: EZ0  
 - Output 04: S/S 1  
 - Output 05: EA1  
 - Output 06: EB1  
 - Output 07: EZ1  
 - Output 08: S/S 2  
 - Output 09: DI0  
 - Output 10: DI1  
 - Output 11: DI2  
 - Output 12: DI3  
 - Output 13: COM  
 - Output 14: DO0  
 - Output 15: DO1

**Robot** 

**Industrial camera** 

**Servo** 

**Stepper** 

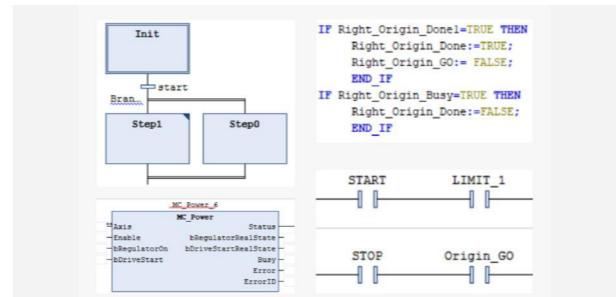
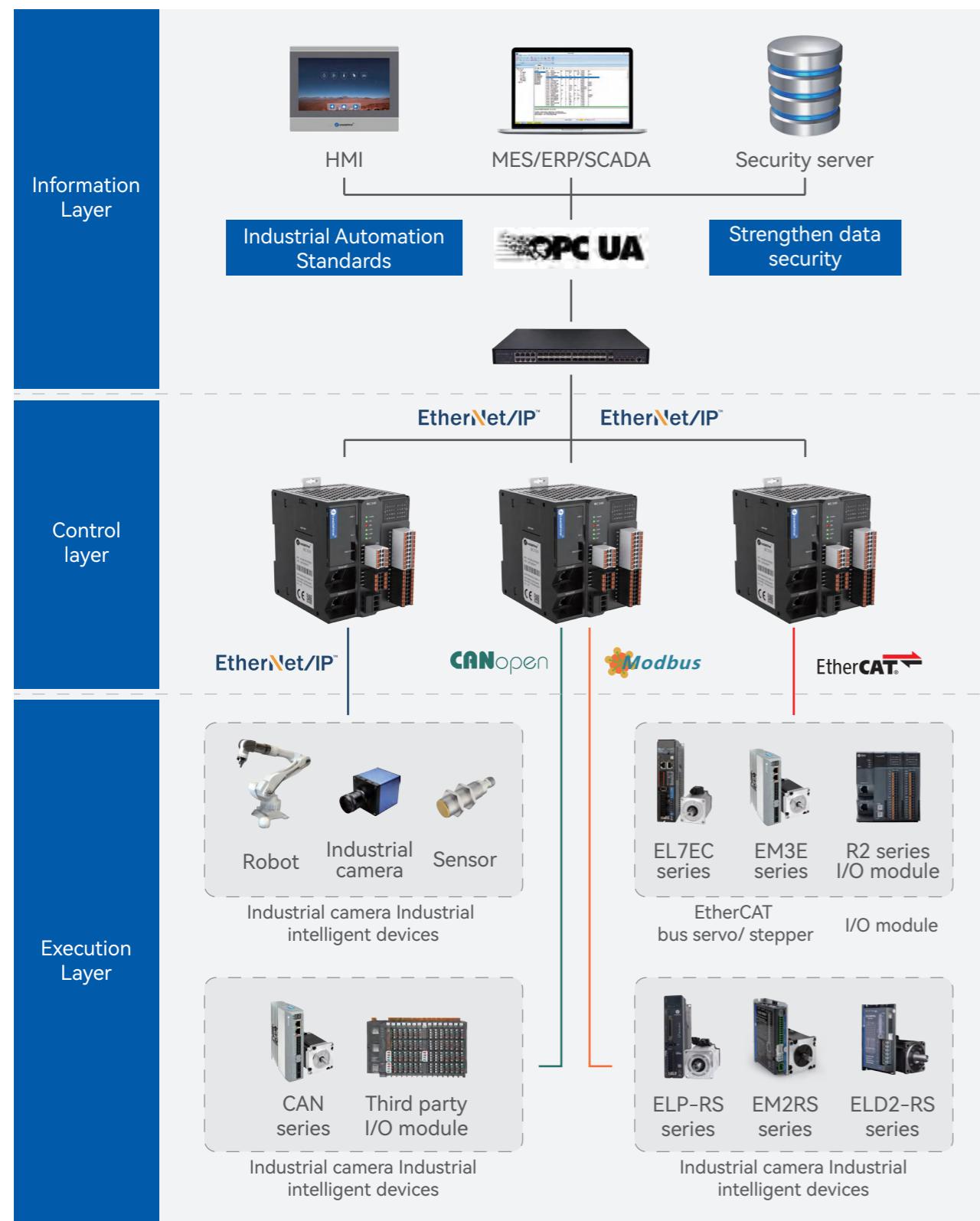
**R2 series i/o module** 

**100M high-speed internal backplane bus,maximum expanding 32 I/O modules**

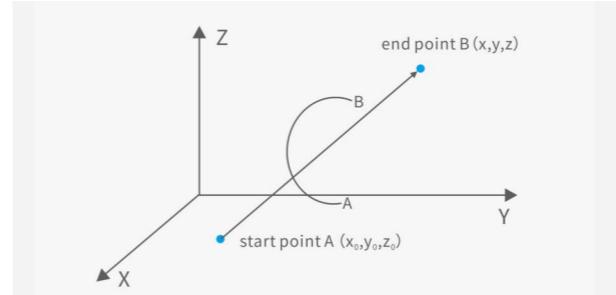
- CPU:Dual core high-speed processor
- I/O,motion control synchronous time:1ms
- synchronous jitter time:1μs
- processing speed: 10ns
- program capacity:20MB
- data capacity: 40MB
- Power-Failure Retention Area:512KB

## Intelligent interconnection

OPC UA is an open international standard communication protocol. It is an industrial communication specification for intelligent manufacturing. It can directly and securely connect with IT systems such as MES/ERP to achieve tamper proof data, strengthen secure transmission, and eliminate interoperability barriers between the Mechanical floor and the information layer, helping traditional enterprises to achieve lean production in factories.



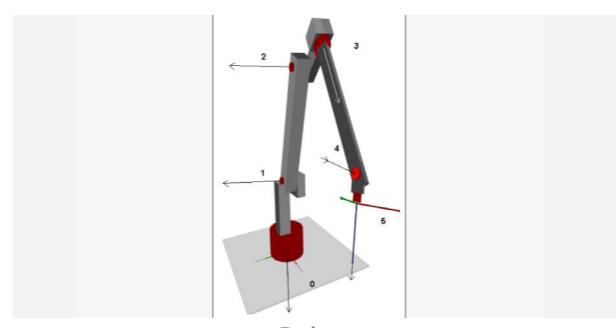
Program language :ST,LD,CFC,SFC,FBD,IL



## Space Interpolation

```
1 N000 G90
2 N010 G92 X0 Y0
3 N020 G00 X-5 Y134
4 N030 G01 X75 Y134
5 N040 X100 Y210
6 N050 X125 Y134
7 N060 X205 Y134
8 N070 X140 Y97
9 N080 X165 Y11
10 N090 X100 Y58
11 N100 X35 Y11
12 N110 X60 Y87
13 N090 X-5 Y134
14 N120
```

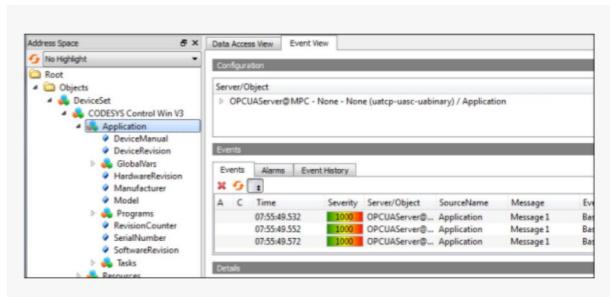
G code



Robot



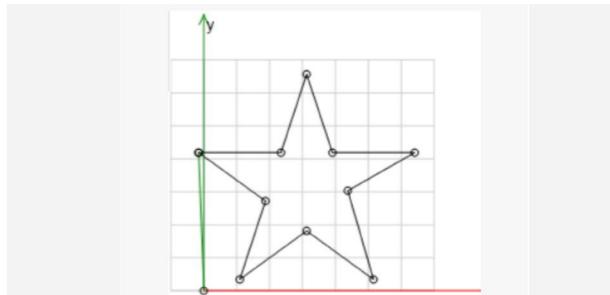
## Online simulation



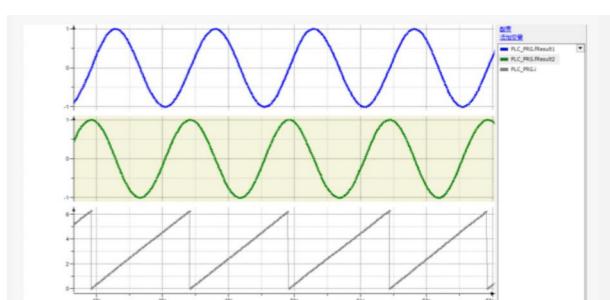
## OPC\_UA informationize function

cam	cam 表	摇杆	摇杆表	X	Y	V	A	J	段类型	最小(...)	最大(...)	最大(...)	最大(...)
●				0	0	0	0	0	Poly5	0	20.000...	0.0516...	0.0002...
●				600	20	0.0285...	0	0					
●				2000	60	0.0285...	0	0	Line	20	60	0.0285...	0
●				2500	80	0	0	0	Poly5	60	79.999...	0.0516...	0.0002...
●				3500	0	0	0	0	Poly5	0	80	0.15	0.0004...

E-CAM



## CNC tool path



## Trace monitor



## Function Library developing

## Product information

### MC500 series PLC specification

Model Specifications	MC508CS	MC516CS	MC532CS
	EtherCAT 8 axes + pulse+dir 6 axes	EtherCAT 16 axes + pulse+dir 6 axes	EtherCAT 32 axes + pulse+dir 6 axes
Axes of Pulse +dir	Local 6 axes 200K pulse output		
Extention Capacity	maximum extend 32 R2 series extension modules		
EtherNET	1* EtherNET port, Modbus , Socket,program upload or download ,debugging		
EtherCAT	EtherCAT master , up to 128 slaves		
serial port communication	RS232*1,RS485*2,free communication protocol,modbus rtu master and slave		
CAN	maximum 31 slave		
Capacity of Program file	20 M Byte		
Capacity of data	40 M Byte		
Power-Failure Retention Area	512K Byte		
USB port	Type-C port, program upload or download,debugging		
SD card slot	user download program,standard micro SD card,FAT32 type,Maximum capacity 32G		
Function	Point to point , E-CAM, Interpolation		
High-speed counter	6 inputs ,200K		
IO Quantity	16 inputs High-speed input/ normal input: 12 inputs 200K/4 inputs 1K(NPN/PNP) High-speed output/ normal output: 12 outputs 200K/4 outputs 10K(NPN)		
RTC clock	RTC		
program software	Leadsys Studio ,Codesys V3.5(SP15)		
Program Language	ST,LD,CFC,SFC,FBD,IL		
Power input	DC 24V		
Power rating	3.6W		
Dimension	L 98.50mm*W 81.75mm*H100.00mm		

### R2 series extension module

#### EtherCAT coupler

Diagram	Model	Bus type	Bus Port	Bus Function	Dimension
	R2EC	EtherCAT	2* RJ45,1 input 1 output,rate : 100M	Complies with EtherCAT bus standards, occupies one slave station, can expand up to 32 modules with one coupler	L 100.92mm* W 42.5mm* H 110mm

#### Digital input module

Diagram	Model	Pins	Input Type	Terminal	Dimension
	PM-1600	16	NPN/PNP	Pressing terminal	L 111.92mm* W 25.9mm* H 101.5mm
	PM-3200	32	NPN/PNP	Pressing terminal	L 111.92mm* W 30.9mm* H 101.5mm
	PM-3200-1	32	NPN/PNP	MIL terminal	L 111.92mm* W 30.9mm* H 101.5mm
	PM-3200-2	32	NPN/PNP	Fujitsu terminal	L 111.92mm* W 30.9mm* H 101.5mm

#### Analog input module

Diagram	Model	Channels	Input Range	Conversion Time	Resolution	Input Type	Dimension
	PM-A0400-IV	4	1V~5V/0V~5V/-5V~5V/0V~10V/-10V~10V/0mA~20mA/4mA~20mA	1ms/4 channels	16-bit ( $\pm 3200$ )	single-ended/differential	L 111.92mm* W 25.9mm* H 101.5mm

## Dimension and parts (PM-1600/PM-3200)

Diagram	Model	Pins	Output Type	Terminal	Dimension
	PM-0016-N	16	NPN	Pressing terminal	L 111.92mm* W 25.9mm* H 101.5mm
	PM-0016-P	16	PNP	Pressing terminal	L 111.92mm* W 25.9mm* H 101.5mm
	PM-0016-R	16	Relay	Pressing terminal	L 111.92mm* W 25.9mm* H 101.5mm
	PM-0032-N	32	NPN	Pressing terminal	L 111.92mm* W 30.9mm* H 101.5mm
	PM-0032-N-1	32	NPN	MIL terminal	L 111.92mm* W 30.9mm* H 101.5mm
	PM-0032-N-2	32	NPN	Fujitsu terminal	L 111.92mm* W 30.9mm* H 101.5mm

## Digital I/O module

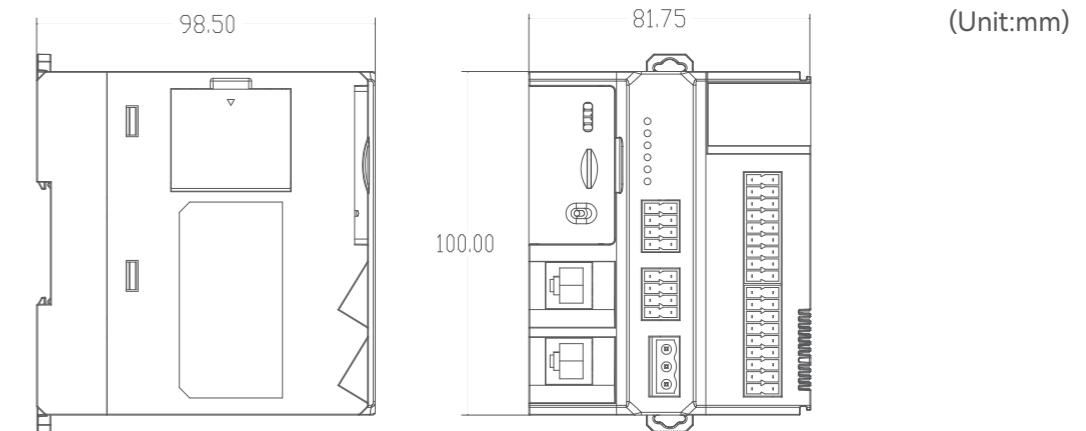
Diagram	Model	Pins	Output Type	Terminal	Dimension	dimension
	PM-1616-N	32	NPN/PNP	NPN	Pressing terminal	L 111.92mm* W 30.9mm* H 101.5mm

## Analog output module

Diagram	Model	Pins	Output Type	Terminal	Dimension	dimension
	PM-A0004-IV	4	1V~5V/0V~5V/ -5V~5V/0V~10V/ -10V~10V/ 0mA~20mA/ 4mA~20mA	1ms/4 channels	16-bit (±3200)	L 111.92mm* W 25.9mm* H 101.5mm

## Dimension

### MC508CS/MC516CS/MC532CS



### Model and label

**MC - 5 - 16 CS - RS**

PLC series  
MC Medium controller

Function series  
5 General type

Customized	
RS	RS485 type
CN	CAN type
blank	Standard

CS Codesys software

EtherCAT axes capacity



Leadshine
Model:MC516CS
POWER INPUT:DC24V 1A
16DI:DC24V NPN/PNP
16DO:DC24V NPN 0.3A
S/N:XXX-XXX-XXX



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